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## Abstract

This document provides guidance on using the Constrained Application Protocol (CoAP) in deep space environments. The document focuses on the approach whereby an IP protocol stack is used for end-to-end communication.

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## 1. Introduction

Deep space communication occurs between devices on or orbiting different celestial bodies (e.g., different planets of the Solar System). Such environments are characterized by long delays (e.g., in the order of minutes or hours), intermittent communication opportunities, limited energy resources, limited computing resources, and relatively low bandwidth [I-D.many-tiptop-usecase].

The Internet Protocol (IP) stack was considered unsuitable for deep space environments more than two decades ago, leading to the design of the Delay-Tolerant Networking (DTN) architecture [RFC4838] and the Bundle Protocol (BP) [RFC5050] [RFC9171]. However, recent work has revisited such assessment, and it has discussed solutions to use the IP protocol stack in deep space communication [I-D.many-deepspace-ip-assessment][I-D.many-tiptop-ip-architecture][I-D.many-tiptop-ip-architecture][I-D.many-tiptop-quic-profile][I-D.many-tiptop-dns][I-D.many-tiptop-email].

The Constrained Application Protocol (CoAP) [RFC7252] is a candidate application-layer protocol for space [I-D.many-tiptop-ip-architecture]. CoAP is based on Representational State Transfer (REST). In CoAP, endpoints called clients make requests with the aim to manipulate resources handled by other endpoints called servers. The latter provide responses back to the clients.

CoAP was designed for constrained devices and constrained networks, which are typical in Internet of Things (IoT) scenarios. CoAP offers several features suitable for its use in deep space environments, including lightweight operation, asynchronous message exchanges, and a significant degree of flexibility. This document provides guidance on the use of CoAP for deep space environments. Use of CoAP over BP [RFC9171] is outside the scope of this document. Note that there is work in progress intended to specify how CoAP can be carried over BP [I-D.ietf-core-coap-bp].

## 2. Terminology

### 2.1. Requirements language

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "NOT RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in BCP14 [RFC2119], [RFC8174], when, and only when, they appear in all capitals, as shown here.

## 3. CoAP transport

### 3.1. Overview and underlying transport

CoAP was originally designed to use UDP as its underlying transport protocol [RFC7252]. The message layer of CoAP over UDP supports optional message reliability, simple congestion control, and flow control. A CoAP message that requires reliable delivery is marked as a Confirmable (CON) message. The recipient needs to send an Acknowledgment (ACK) message to confirm successful reception of a CON message. A sender uses a retransmission mechanism with a default timeout and an exponential back-off between retransmissions. A CoAP message that does not require reliability is marked as a Non-confirmable (NON) message. NON messages are not acknowledged.

Subsequently, CoAP was adapted to be carried also over other transports, such as TCP, Transport Layer Security (TLS), and WebSockets [RFC8323]. However, due to the long delays in deep space environments, initial handshake exchanges (e.g., the three-way handshake of TCP) penalize communication performance significantly.

In addition, when TCP is used as the underlying transport-layer protocol, the ability of optionally requesting reliable delivery for a given message (as offered by CoAP over UDP) is lost. Two further advantages of UDP-based CoAP transport are a shorter header size and support for multicast. Therefore, this document will focus on CoAP as used over UDP as the underlying transport [RFC7252].

### 3.2. Main CoAP parameters and times relevant to deep space environments

This section discusses the main parameters and times that are relevant in the context of deep space environments. (Note that the complete set of parameters, assumptions, default values, and related times in CoAP can be found in Section 4.8 of RFC7252.)

As a congestion control measure, the maximum number of outstanding interactions between a client and a given server is limited to `NSTART`, which is set to a default value of 1. A greater value for `NSTART` can be used only when mechanisms that ensure congestion control safety are used.

The main parameters related with CON messages are indicated next.

`ACK_TIMEOUT` and `ACK_RANDOM_FACTOR`. These two parameters determine the duration of the initial retransmission timeout, which is set to a randomly chosen value between `ACK_TIMEOUT` and `ACK_TIMEOUT * ACK_RANDOM_FACTOR`. The default values for `ACK_TIMEOUT` and `ACK_RANDOM_FACTOR` are 2 s and 1.5, respectively. Therefore, the default initial retransmission timeout in CoAP is between 2 and 3 s.

`ACK_TIMEOUT` should be set to a value of at least the expected RTT, which in deep space may be up to several orders of magnitude greater than the default one (see Appendix A of [I-D.ietf-core-coap-bp]).

`ACK_RANDOM_FACTOR` needs to be at least equal to or greater than 1.0. The default value of 1.5 is intended to avoid synchronization effects among different senders when RTTs are in the order of seconds. However, the greater latency in deep space environments may reduce the risk of synchronization effects therein. In such case, a lower `ACK_RANDOM_FACTOR` may help reduce total message delivery latency when retries are performed.

`MAX_RETRANSMIT`. This parameter defines the maximum number of retries for a given CON message. The default value for this parameter is 4. Since there is an exponential back-off between retransmissions, and considering the delay values in deep space environments, it may be suitable to set this parameter to a value lower than the default one.

The following assumptions on the characteristics of the network and the nodes need to be considered:

MAX\_LATENCY is the maximum time a datagram is expected to take from the start of its transmission to the completion of its reception. In RFC 7252, this value is arbitrarily set to 100 s, which is close to the historic Maximum Segment Lifetime (MSL) of 120 s defined in the TCP specification [RFC9293]. However, such value assumes communication between devices on Earth. In deep space environments, MAX\_LATENCY may need to be increased by one or more orders of magnitude (see Appendix A of [I-D.ietf-core-coap-bp]).

PROCESSING\_DELAY is the time since a node receives a CON message until it transmits an ACK in response. In RFC 7252, this value is assumed to be of at most the default ACK\_TIMEOUT value of 2 s. For the sake of limiting latency, it is assumed that the same value can be used also in deep space environments.

A relevant CON message derived time is EXCHANGE\_LIFETIME. This time indicates the maximum possible time since a CON message is sent for the first time, until ACK reception (which may potentially occur after several retries). EXCHANGE\_LIFETIME includes the following components: the total time since the first transmission attempt of a CON message until the last one (called MAX\_TRANSMIT\_SPAN in RFC 7252), a MAX\_LATENCY for the CON, PROCESSING\_DELAY, and a MAX\_LATENCY for the ACK. The default value for EXCHANGE\_LIFETIME is 247 s. However, in deep space environments, and considering the modified values for protocol parameters and the network characteristics described above, EXCHANGE\_LIFETIME may have to be even several orders of magnitude greater than the default one (e.g., at least 2-3 orders of magnitude in deep space, See Appendix A of [I-D.ietf-core-coap-bp]).

The main time related with NON messages is NON\_LIFETIME. This is the time since a NON message is transmitted until its Message ID can be safely reused. This time is actually equal to MAX\_LATENCY, therefore its default value is 100 s. However, as described earlier, in deep space environments it may need to be increased by one or more orders of magnitude (see Appendix A of [I-D.ietf-core-coap-bp]).

Note that implementations may also need to be adapted if they have been designed to use 8-bit timers to handle CON or NON message lifetimes (e.g., to retire Message IDs) in seconds.

#### 4. Caching

RFC 7252 states that "CoAP endpoints MAY cache responses in order to reduce the response time and network bandwidth consumption on future, equivalent requests". Note that caching may also offer energy consumption savings.

In deep space scenarios, the efficiency provided by the caching feature is particularly suitable. Nevertheless, it needs to be adapted to the characteristics of the scenario, especially in terms of latency.

A cached response can be reused as long as it is considered "fresh". In order to determine the freshness of a response, the origin server uses the Max-Age option to indicate that the response is to be considered not fresh after its age is greater than the specified number of seconds.

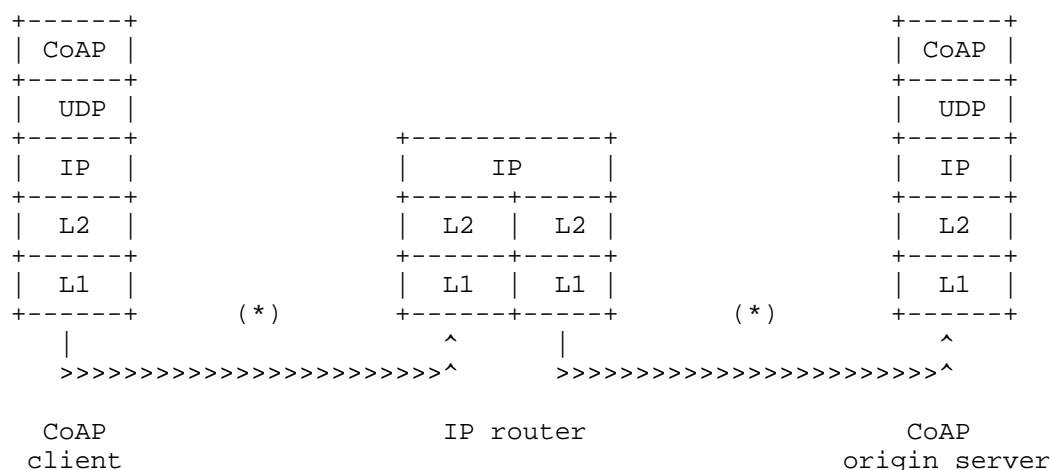
The default Max-Age value is 60 seconds. When a response does not carry a Max-Age option, it is considered to have an associated Max-Age value equal to the default one. Also, the Max-Age value is intended to be current at the time of transmission. Therefore, considering the latencies of deep space environments, if a response is intended to be cacheable, the origin server needs to include a Max-Age option of an appropriate value with the response (the maximum possible option value being  $2^{32}-1$  seconds (i.e., ~136.1 years)). Of course, it will only make sense to consider that a response is cacheable if it can be fresh for a time greater than the expected latency between the origin server and the caching CoAP endpoint. If a CoAP endpoint receives a response known to be not fresh (e.g., if communication latency is greater than its associated Max-Age), the CoAP endpoint will not store the response.

#### 5. Proxying

RFC 7252 defines a "proxy" as "An intermediary that mainly is concerned with forwarding requests and relaying back responses, possibly performing caching, namespace translation, or protocol translation in the process". The same specification also states that "A proxy is a CoAP endpoint that can be tasked by CoAP clients to perform requests on their behalf". Among others, this can be useful "to service the response from a cache in order to reduce response time and network bandwidth or energy consumption". The latter are advantages that may be desirable as well in deep space environments.

Depending on the protocol(s) supported at each side of the proxy, a proxy can be a "CoAP-to-CoAP proxy", which "maps from a CoAP request to a CoAP request", or a "cross-proxy", which "translates between

[I-D.many-tiptop-usecase].)



routers between the latter and the CoAP origin server.

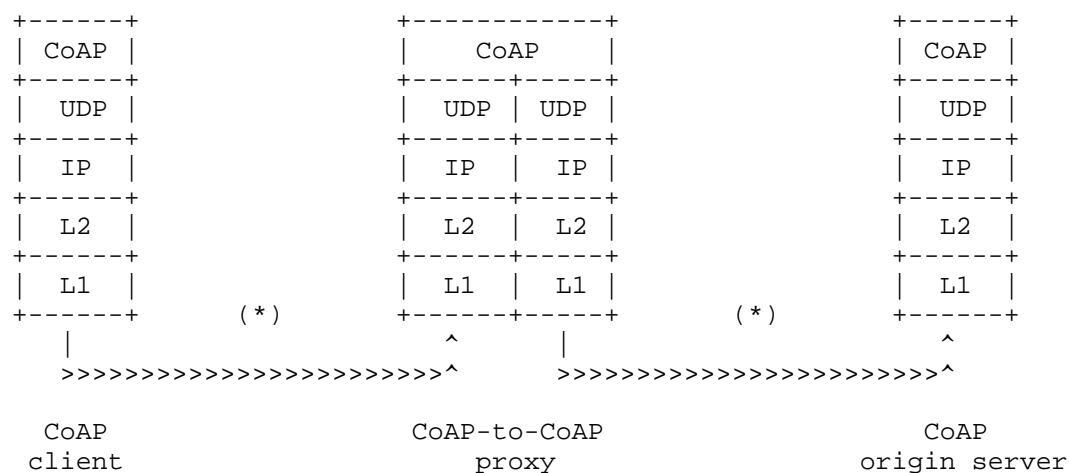


Figure 2: CoAP-to-CoAP proxy scenario. (\*) There may be zero or more IP routers between the CoAP client and the CoAP-to-CoAP proxy, and zero or more IP routers between the CoAP-to-CoAP proxy and the CoAP origin server.

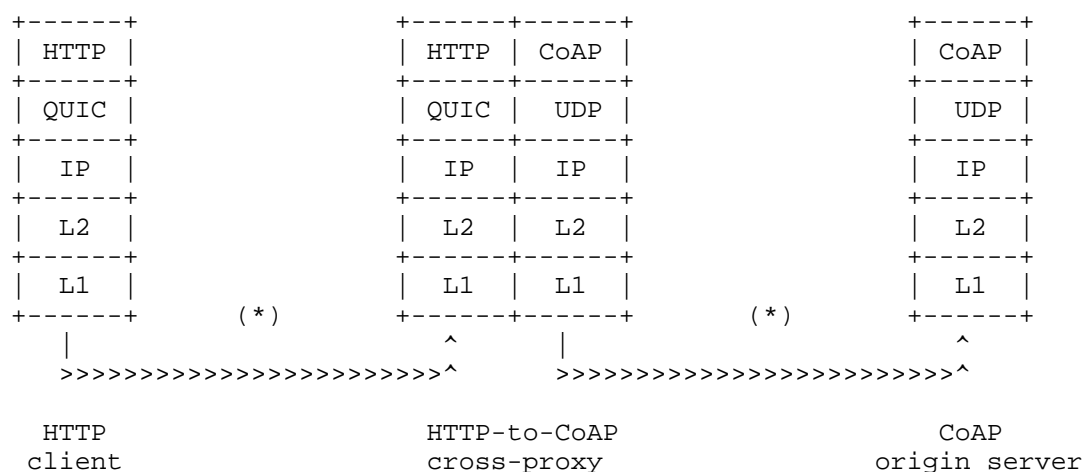


Figure 3: HTTP-to-CoAP proxy scenario. (\*) There may be zero or more IP routers between the HTTP client and the HTTP-to-CoAP cross-proxy, and zero or more IP routers between the cross-proxy and the CoAP origin server.



## 6. Observe

The Observe Option allows a server to send notifications carrying a representation of the current state of a resource to interested clients called observers [RFC7641]. The latter need to initially register at a specific server that they are interested in being notified whenever the resource state changes. There is also work in progress intended to allow a CoAP client to limit notifications to those where the state representation of a resource fulfills certain constraints (e.g., a minimum/maximum value) [I-D.ietf-core-conditional-attributes].

Observe generally provides significant performance benefits, since, after the registration, the client does not have to send a request to receive a notification. This feature is particularly beneficial in deep space environments, where end-to-end latency is high, and energy and bandwidth resources may be constrained.

As per the Observe specification, when the time between the two last notifications received by a CoAP client is greater than 128 seconds, it can be concluded that the last one received is also the latest sent by the server. The duration of 128 seconds was chosen as a number greater than the default MAX\_LATENCY value of the base CoAP specification. When CoAP is used in deep space environments, the duration of 128 seconds may be insufficient. In such case, the duration needs to be chosen as a value greater than the MAX\_LATENCY of the scenario (See Appendix A of [I-D.ietf-core-coap-bp]).

## 7. Block-wise transfers

### 7.1. Overview

There exist two CoAP specifications that define functionality that allows to carry large CoAP payloads (i.e., payloads that do not fit a single packet) by means of block-wise transfers: [RFC7959] and [RFC9177].

RFC 7959 defines the Block1 and Block2 options, whereby, in a block-wise transfer, a CoAP endpoint can only ask for (or send) the next block after the previous block has been transferred. Furthermore, RFC 7959 recommends the use of CON messages. Therefore, communication follows a stop-and-wait pattern.

RFC 9177, which defines the Q-Block1 and Q-Block2 options, is particularly suitable for deep space environments, as it enables block-wise transfers using NON messages. Thus, blocks can be transmitted serially without having to wait for a response or next request from the remote CoAP peer. Recovery of multiple missing blocks (which can be reported at once in a single CoAP message) is also supported.

The Q-Block1 option is defined for payload-bearing (e.g., POST, PUT, FETCH, PATCH, and iPATCH) requests and their responses. The Q-Block2 option is useful for requests (e.g., GET, POST, PUT, FETCH, PATCH, and iPATCH) and their payload-bearing responses.

## 7.2. Main related parameters

The following new parameters are defined by RFC 9177, for use with NON messages and the Q-Block1 and Q-Block2 options: MAX\_PAYLOADS, NON\_TIMEOUT, NON\_TIMEOUT\_RANDOM, NON\_RECEIVE\_TIMEOUT, NON\_MAX\_RETRANSMIT, NON\_PROBING\_WAIT, and NON\_PARTIAL\_TIMEOUT.

MAX\_PAYLOADS indicates the number of consecutive blocks an endpoint can transmit without eliciting a message from the other endpoint. The default value defined for this parameter is 10, which is in line with the initial window size currently defined for TCP [RFC6928].

TO-DO: MAX\_PAYLOADS recommended setting?

NON\_TIMEOUT is the minimum time between sending two consecutive sets of MAX\_PAYLOADS blocks that correspond to the same body. The actual time between sending two consecutive sets of MAX\_PAYLOADS blocks is called NON\_TIMEOUT\_RANDOM, which is calculated as  $\text{NON\_TIMEOUT} * \text{ACK\_RANDOM\_FACTOR}$ . In RFC 9177, NON\_TIMEOUT is defined as having the same value as ACK\_TIMEOUT. ACK\_RANDOM\_FACTOR is set to 1.5, following RFC 7252. As a result, by default, NON\_TIMEOUT\_RANDOM is equal to a randomly chosen value between 2 and 3 s.

The NON\_TIMEOUT\_RANDOM inactivity interval described above is introduced to avoid causing congestion due to the transmission of MAX\_PAYLOADS itself. As discussed in Section 3.2, in deep space environments, ACK\_TIMEOUT should be set to a value greater than default. However, when CoAP is used in such environments, NON\_TIMEOUT, and thus NON\_TIMEOUT\_RANDOM, need to be adjusted considering the characteristics of the end-to-end path, independent of ACK\_TIMEOUT.

NON\_RECEIVE\_TIMEOUT is the initial time that a receiver will wait for a missing block within MAX\_PAYLOADS before requesting retransmission for the first time. Every time the missing payload is re-requested,

the time to wait value doubles. `NON_RECEIVE_TIMEOUT` has a default value of `2*NON_TIMEOUT`. As described earlier, when CoAP is used in deep space environments, `NON_TIMEOUT` needs to be adjusted considering the characteristics of the end-to-end path.

`NON_MAX_RETRANSMIT` is the maximum number of times a request for the retransmission of missing payloads can occur without a response from the remote peer. By default, `NON_MAX_RETRANSMIT` has the same value as `MAX_RETRANSMIT` (Section 4.8 of [RFC7252]). Accordingly, when CoAP is used in deep space environments, the same considerations regarding `MAX_RETRANSMIT` in Section 3.2 apply to `NON_MAX_RETRANSMIT` as well. That is, when CoAP is used in space, while the default value for this parameter is 4, it may be suitable to set this parameter to a value lower than the default one.

## 8. Message aggregation

The CoAP over BP specification introduces the CoAP Payload-length option, which allows CoAP messages destined to the same endpoint to be aggregated and carried as the payload of a single encapsulating lower-layer data unit [I-D.ietf-core-coap-bp]. When CoAP is used over UDP (as is the focus of the present document), the encapsulating lower-layer data unit is a UDP datagram.

A concatenation of messages that carry the Payload-length option is called an Aggregate message [I-D.ietf-core-coap-bp]. In some scenarios, message aggregation may be compatible with application requirements, while allowing to reduce protocol overhead and increase node and network performance.

## 9. CoAP group communication

In CoAP group communication, a client sends multicast CoAP request messages over UDP/IP multicast as default transport. Each server in the target destination group sends a response message back to the client over UDP/IP unicast, although a server can suppress its response for several reasons (see Section 3.1.2 of [I-D.ietf-core-groupcomm-bis]).

[I-D.ietf-core-groupcomm-bis] defines the minimum time between reuse of Token values for different group requests, `MIN_TOKEN_REUSE_TIME`, to be greater than:

$$\text{MIN\_TOKEN\_REUSE\_TIME} = (\text{NON\_LIFETIME} + \text{MAX\_LATENCY} + \text{MAX\_SERVER\_RESPONSE\_DELAY})$$

where `MAX_SERVER_RESPONSE_DELAY` is the expected maximum response delay over all servers that the client can send a CoAP group request to. [I-D.ietf-core-groupcomm-bis] states that, "using the default CoAP parameters, the Token reuse time MUST be greater than 250 seconds plus `MAX_SERVER_RESPONSE_DELAY`".

[I-D.ietf-core-groupcomm-bis] also adds that, while a possible approach is to generate a new unique Token for every new group request, if a client has to reuse Token values for some reason, `MAX_SERVER_RESPONSE_DELAY = 250` seconds is a suitable value, therefore leading to a time between Token reuses greater than `MIN_TOKEN_REUSE_TIME = 500` seconds. However, in a deep space scenario, `MIN_TOKEN_REUSE_TIME` needs to be determined considering the latency of that scenario.

## 10. Security

The base CoAP specification defines a binding to Datagram Transport Layer Security (DTLS) [RFC7252][RFC9147]. There are four possible DTLS security modes: NoSec, PreSharedKey, RawPublicKey, and Certificate. The NoSec and RawPublicKey modes are mandatory to implement.

Subsequently, Object Security for Constrained RESTful Environments (OSCORE) was specified [RFC8613]. OSCORE is a security protocol that allows to protect an application-layer data payload end-to-end, even in the presence of untrusted proxies in the path between two endpoints. The Group OSCORE protocol is also being used to secure CoAP group communication [I-D.ietf-core-oscore-groupcomm], in contrast with the initial CoAP group communication specification [RFC 7390], which assumed that CoAP over IP multicast was not encrypted, nor authenticated, nor access controlled.

In OSCORE, the communicating endpoints require a shared security context. An interesting aspect of OSCORE for deep space environments is that, if the materials used to establish such context are pre-shared, there is no initial handshake prior to actual communication, thus avoiding a significant latency penalty.

In order to offer protection against replay attacks, OSCORE uses by default an anti-replay sliding window, with a window size of 32 [RFC 8613]. If a greater window size is deemed necessary (e.g., due to high latency in an intended scenario), that window size needs to be known by both sender and receiver at the moment of security context establishment.

## 11. IANA Considerations

This document has no IANA considerations

## 12. Security Considerations

TO-DO

## 13. Acknowledgments

Marisa Catalan and Julia Igual from i2cat contributed to this document.

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## Appendix A. Applicability in store-and-forward LEO satellite environments

Communications characteristics similar to those of deep space (long delays -e.g., in the order of minutes or hours-, intermittent communication opportunities, limited energy resources, and relatively low bandwidth) can be found in Non-Terrestrial Networks (NTN) based on sparse Low Earth Orbit (LEO) satellite constellations that provide direct connectivity to Internet of Things (IoT) devices on Earth, albeit with discontinuous coverage. In such cases, an IoT device may need to wait until it is visited by a satellite to be able to transmit its data. In addition, if the satellite does not have an immediately available link with a ground station or with a second satellite, the first satellite needs to perform store-and-forward operation. This paradigm supports delay-tolerant, non-real-time communication services. Note that extensions to enable store-and-forward operation are being standardized by 3GPP in Release 19 [3GPP].

The guidance offered in this document may also be useful in the store-and-forward LEO satellite environments described in the previous paragraph.

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